
Exoskeletons supporting balance control - the BALANCE project

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Résumé

Résumé: à définir **Bio:** *Jan F. Veneman, Health - Rehabilitation Robotics, Tecnalia Research and Innovation, Spain. Jan is mechanical engineer and doctor in biomechatronics with University of Twente, Netherlands. Since 2008 working in Tecnalia (former Fatronik) as project manager and senior researcher on human-robot interaction, rehabilitation of gait and posture, and robotic orthoses for gait; lines in which he was active since 2002, starting with the development of the LOPES gait rehabilitation robot. Since 2013 he is coordinating the EC-FP7 consortium research Project BALANCE, on the development of a robotic exoskeleton with self-balancing control and since 2012 international expert in several ISO and IEC standardization working groups related to wearable robotics.*

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